

Shigley's Mechanical Engineering Design

2024 Release

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SHIGLEY'S MECHANICAL ENGINEERING DESIGN, 2024 RELEASE

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This book is printed on acid-free paper.

1 2 3 4 5 6 7 8 9 LWI 29 28 27 26 25 24

ISBN 978-1-265-47269-6 (bound) MHID 1-265-47269-6 (bound) ISBN 978-1-266-73171-6 (loose-leaf) MHID 1-266-73171-7 (loose-leaf)

Portfolio Manager: *Beth Bettcher* Product Developer: *Theresa Collins* Marketing Manager: *Lisa Granger* Content Project Managers: *Renee Colbert, Rachael Hillebrand* Manufacturing Project Manager: *Laura Fuller* Content Licensing Specialist: *Lorraine Buczek* Cover Image: *Courtesy of Dee Dehokenanan* Compositor: *Aptara*[®], *Inc.*

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Library of Congress Cataloging-in-Publication Data

- Names: Nisbett, J. Keith, author. | Budynas, Richard G. (Richard Gordon), author.
- Title: Shigley's mechanical engineering design / J. Keith Nisbett, Associate Professor of Mechanical Engineering, Missouri University of Science and Technology, Richard G. Budynas, Professor Emeritus, Kate Gleason College of Engineering, Rochester Institute of Technology.
- Description: 2024 release. | New York, NY : McGraw Hill LLC, 2024. | Includes index.
- Identifiers: LCCN 2023028087 (print) | LCCN 2023028088 (ebook) | ISBN 9781265472696 (bound edition) | ISBN 1265472696 (bound edition) | ISBN 9781266731716 (loose-leaf edition) | ISBN 1266731717 (loose-leaf edition) | ISBN 9781266738050 (ebook other)

Subjects: LCSH: Machine design.

- Classification: LCC TJ230 .S5 2024 (print) | LCC TJ230 (ebook) | DDC 621.8/15—dc23/eng/20230729
- LC record available at https://lccn.loc.gov/2023028087

LC ebook record available at https://lccn.loc.gov/2023028088

The Internet addresses listed in the text were accurate at the time of publication. The inclusion of a website does not indicate an endorsement by the authors or McGraw Hill LLC, and McGraw Hill LLC does not guarantee the accuracy of the information presented at these sites.

Dedication

To Richard Budynas, in appreciation of his mentorship, his attention to detail, and his contributions to the engineering profession.

J. Keith Nisbett

Joseph Edward Shigley (1909–1994) is undoubtedly one of the most well-known and respected contributors in machine design education. He authored or coauthored eight books, including *Theory of Machines and Mechanisms* (with John J. Uicker, Jr.), and *Applied Mechanics of Materials*. He was coeditor-in-chief of the well-known *Standard Handbook of Machine Design*. He began *Machine Design* as sole author in 1956, and it evolved into *Mechanical Engineering Design*, setting the model for such textbooks. He contributed to the first five editions of this text, along with coauthors Larry Mitchell and Charles Mischke. Uncounted numbers of students across the world got their first taste of machine design with Shigley's textbook, which has literally become a classic. Nearly every mechanical engineer for the past half century has referenced terminology, equations, or procedures as being from "Shigley." McGraw Hill is honored to have worked with Professor Shigley for more than 40 years, and as a tribute to his lasting contribution to this textbook, its title officially reflects what many have already come to call it—*Shigley's Mechanical Engineering Design*.

Having received a bachelor's degree in Electrical and Mechanical Engineering from Purdue University and a master of science in Engineering Mechanics from the University of Michigan, Professor Shigley pursued an academic career at Clemson College from 1936 through 1954. This led to his position as professor and head of Mechanical Design and Drawing at Clemson College. He joined the faculty of the Department of Mechanical Engineering of the University of Michigan in 1956, where he remained for 22 years until his retirement in 1978.

Professor Shigley was granted the rank of Fellow of the American Society of Mechanical Engineers in 1968. He received the ASME Mechanisms Committee Award in 1974, the Worcester Reed Warner Medal for outstanding contribution to the permanent literature of engineering in 1977, and the ASME Machine Design Award in 1985.

Joseph Edward Shigley indeed made a difference. His legacy shall continue.

J. Keith Nisbett is an Associate Professor of Mechanical Engineering at the Missouri University of Science and Technology. He has more than 40 years of experience with using and teaching from this classic textbook. He was awarded the BS, MS, and PhD of the University of Texas at Arlington.

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Preface

Objectives

This text is intended for students beginning the study of mechanical engineering design. The focus is on blending fundamental development of concepts with practical specification of components. Students of this text should find that it inherently directs them into familiarity with both the basis for decisions and the standards of industrial components. For this reason, as students transition to practicing engineers, they will find that this text is indispensable as a reference text. The objectives of the text are to:

- Cover the basics of machine design, including the design process, engineering mechanics and materials, failure prevention under static and variable loading, and characteristics of the principal types of mechanical elements.
- Offer a practical approach to the subject through a wide range of real-world applications and examples.
- Encourage readers to link design and analysis.
- Encourage readers to link fundamental concepts with practical component specification.

New to This Release

Enhancements and modifications to this release are described in the following summaries:

- Chapter 3, *Load and Stress Analysis.* This foundational topic is often assumed to be understood from a previous course in Mechanics of Materials. However, students benefit greatly from a review that focuses their attention on the conceptual basis behind the math, and on being able to home in on the most needed aspects for machine design. This core topic is given a fresh presentation. The goal is to properly identify critical stress elements. This requires clarity in using free-body diagrams, identifying internal stresses, visualizing a stress element, and determining extreme stresses from the stress element.
- Chapter 4, *Deflection and Stiffness*. The coverage of singularity functions in Section 4–6 has been expanded to cover the method sufficiently without assuming prior exposure. The coverage from Section 3–3 has been merged into an expanded consolidated coverage in Section 4–6. The Euler–Bernoulli beam theory is more thoroughly explained in Section 4–3.
- Chapter 14, *Spur and Helical Gears*. The AGMA safety factors are now treated as design factors (as defined by AGMA) to account for unquantifiable aspects of the application. New factors of safety are defined to represent the typical comparison of stress to allowable stress. Also, new factors of safety are introduced to allow linear comparison of load-based failure.

- Chapter 10, *Mechanical Springs*. For fatigue loading of helical compression springs, the Zimmerli experiments and the recommendations based on them are better explained.
- Chapter 1, *Introduction to Mechanical Engineering Design*. This chapter has been generally edited for cleaner presentation. Notable changes are found in Sections 1–9, 1–10, and 1–11 with regard to stress, strength, uncertainty, and factor of safety.

The following sections received notable improvements in presentation:

Section 1–5 The Design Engineer's Professional	Section 3-15 Stresses in Rotating Rings
Responsibilities	Section 4–3 Deflection Due to Bending
Section 1–9 Stress and Strength	Section 4–6 Beam Deflections by Singularity Functions
Section 1–10 Uncertainty	Section 5–3 Failure Theories
Section 1–11 Design Factor and Factor of Safety	Section 6–3 Crack Nucleation and Propagation
Section 3–1 Equilibrium and Free-Body Diagrams	(additional failure examples)
Section 3–2 Shear Force and Bending Moments in Beams	Section 8-2 The Mechanics of Power Screws
Section 3–4 Stress	Section 10-4 Compression Springs (presetting)
Section 3-5 Cartesian Stress Components	Section 10–9 Fatigue Loading of Helical Compression
Section 3–6 Mohr's Circle for Plane Stress	Springs
Section 3–7 General Three-Dimensional Stress	Section 13–7 Interference (new interference tables)
Section 3–9 Uniformly Distributed Stresses (direct shear)	Section 14–8 Overload Factor K_o
Section 3-11 Shear Stresses for Beams in Bending	Section 14–17 Safety Factors S_F and S_H
(new Example 3–9)	Section 14-18 Analysis (Factors of safety; updated
Section 3–12 Torsion (Noncircular Cross Sections;	example problems; updated summary pages)
Power Relations)	Section 14-19 Design of a Gear Mesh (updated
Section 3-14 Stresses in Pressurized Cylinders	example problem)

In keeping with the well-recognized accuracy and consistency within this text, minor improvements and corrections are made throughout with each release. Many of these are in response to the diligent feedback from the community of users.

Instructor Supplements

Additional media offerings available in the Instructor Resources include:

- *Solutions manual.* The instructor's manual contains solutions to most end-of-chapter nondesign problems.
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- Strengthening art guidelines to improve accessibility by ensuring meaningful text and images are distinguishable and perceivable by users with limited color vision and moderately low vision.

Acknowledgments

The authors would like to acknowledge those who have contributed to this text for over 50 years. Input from instructors, students, and engineers is instrumental in keeping this text current and clean from errors.

Reviewers of This Release

Milo Rice, California State University, Fullerton Mark Hapstack, Greenville Technical College Matthew Brady, Greenville Technical College Naga Aditya Musunuri, Indiana Institute of Technology

James Gerard Freygang, *Ivy Tech Community College* Valmiki Sooklal, *Kennesaw State University* Shane A. Brauer, *Mississippi State University* Rungun Nathan, *Penn State Berks* Zhongming Liang, Purdue University Fort Wayne Nuri Zeytinoglu, Purdue University Northwest William Palm, Roger Williams University Keivan Davami, University of Alabama Todd Nelson, University of Southern Indiana Brendan O'Toole, University of Nevada, Las Vegas Louie Yaw, Walla Walla University Gene Liao, Wayne State University Richard Meyer, Western Michigan University This is a list of common symbols used in machine design and in this book. Specialized use in a subject-matter area often attracts fore and post subscripts and superscripts. To make the table brief enough to be useful, the symbol kernels are listed. See Table 14–1 for spur and helical gearing symbols, and Table 15–1 for bevel-gear symbols.

Α	Area, coefficient
a	Distance
В	Coefficient, bearing length
Bhn	Brinell hardness
b	Distance, fatigue strength exponent, Weibull shape parameter, width
С	Basic load rating, bolted-joint constant, center distance, coefficient of
	variation, column end condition, correction factor, specific heat
	capacity, spring index, radial clearance
С	Distance, fatigue ductility exponent, radial clearance
COV	Coefficient of variation
D	Diameter, helix diameter
d	Diameter, distance
Ε	Modulus of elasticity, energy, error
е	Distance, eccentricity, efficiency, Naperian logarithmic base
F	Force, fundamental dimension force
f	Coefficient of friction, frequency, function
fom	Figure of merit
G	Torsional modulus of elasticity
8	Acceleration due to gravity, function
Н	Heat, power
H_B	Brinell hardness
HRC	Rockwell C-scale hardness
h	Distance, film thickness
\hbar_{CR}	Combined overall coefficient of convection and radiation heat transfer
Ι	Integral, linear impulse, mass moment of inertia, second moment of area
i	Index
i	Unit vector in x-direction
J	Mechanical equivalent of heat, polar second moment of area, geometry
	factor
j	Unit vector in the y-direction
K	Service factor, stress-concentration factor, stress-augmentation factor,
	torque coefficient
k	Marin endurance limit modifying factor, spring rate
k	Unit vector in the <i>z</i> -direction
L	Length, life, fundamental dimension length

L	Life in hours
l	Length
Μ	Fundamental dimension mass, moment
Μ	Moment vector, mobility vector
т	Mass, slope, strain-strengthening exponent
Ν	Normal force, number, rotational speed, number of cycles
n	Load factor, rotational speed, factor of safety
n_d	Design factor
<i>P</i>	Force, pressure, diametral pitch
PDF	Probability density function
p	Pitch, pressure, probability
Q	First moment of area, imaginary force, volume
q	Distributed load, notch sensitivity
R	Radius, reaction force, reliability, Rockwell hardness, stress ratio,
D	reduction in area
ĸ	Vector reaction force
r	Radius
r	Distance vector
3	Distance complexity deviation stores
S T	Temperature, televance, tensue, fundamental dimension time
1 T	Temperature, torerance, torque, fundamental dimension time
1	Distance time telerence
ι 17	Strain energy
U 11	Strain energy per unit volume
u V	Linear velocity shear force
v	Linear velocity, shear force
W	Cold-work factor load weight
w	Distance gan load intensity
X	Coordinate, truncated number
x	Coordinate, true value of a number. Weibull parameter
Y	Coordinate
v	Coordinate, deflection
Z	Coordinate, section modulus, viscosity
z	Coordinate, dimensionless transform variable for normal distributions
α	Coefficient, coefficient of linear thermal expansion, end-condition for
	springs, thread angle
β	Bearing angle, coefficient
Δ	Change, deflection
δ	Deviation, elongation
ϵ	Eccentricity ratio
ε	Engineering strain
$\tilde{\epsilon}$	True or logarithmic strain
$\tilde{\epsilon}_{f}$	True fracture strain
ε_{f}^{\prime}	Fatigue ductility coefficient
Γ́	Gamma function, pitch angle
γ	Pitch angle, shear strain, specific weight
λ	Slenderness ratio for springs
μ	Absolute viscosity, population mean

 ν Poisson ratio

ω	Angular velocity, circular frequency
ϕ	Angle, wave length
ψ	Slope integral
ρ	Radius of curvature, mass density
σ	Normal stress
σ_a	Alternating stress, stress amplitude
σ_{ar}	Completely reversed alternating stress
σ_m	Mean stress
σ_0	Nominal stress, strength coefficient or strain-strengthening coefficient
σ_{f}^{\prime}	Fatigue strength coefficient
$\ddot{\tilde{\sigma}}$	True stress
$ ilde{\sigma}_{f}$	True fracture strength
σ'	Von Mises stress
$\hat{\sigma}$	Standard deviation
au	Shear stress
θ	Angle, Weibull characteristic parameter
¢	Cost per unit weight
\$	Cost



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